Importance Sampling Simulation of Queues with Time-Varying Rates

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Introduction

- Rare event in a queueing model: large queue;
- Estimate efficiently the probability;
- By application of importance sampling algorithms;
- Analysis of the rare event probability (large deviations);
- Analysis of complexity of algorithms;

The Queueing Model: $M_t/M/1$

Arrivals according to nonhomogeneous Poisson process;



- Exponential services with rate μ;
- Single server; infinite waiting room; FCFS;
- X(t) number of customers present at time *t*;
- Interarrival times U_1, U_2, \ldots ;
- ▶ Service durations *V*₁, *V*₂, . . .;
- ► Stability: λ < μ;</p>

Sequence of Queues

- Parameter $n = 1, 2, \ldots, n \to \infty$;
- Sequence $\{X_n(t) : t \ge 0; n = 1, 2, ...\}$ of $M_t/M/1$ queues;
- Interarrival times:
 - $U_1^{(n)}, U_2^{(n)}, \ldots;$
 - Such that U_1, U_2, \ldots defined by $U_j = nU_i^{(n)}$ are as on previous slide;
- Service times:
 - $V_1^{(n)}, V_2^{(n)}, \ldots;$
 - Such that V_1, V_2, \ldots defined by $V_j = nV_j^{(n)}$ are as on previous slide;
- Interpretation: rates are n-times faster;

Rare Event

• Let $X_n(t)$ number of customers present at time t in the n-queue;

Denote

$$X^{(n)}(t) = \frac{1}{n} X_n(t), \quad t \ge 0;$$

Rare Event Problem

Fix \bar{x}, \bar{y}, T ; compute the overflow probability

$$\ell_n = \mathbb{P}\left(X^{(n)}(T) \ge \overline{y} \,|\, X^{(n)}(0) = \overline{x}\right)$$

for large n.

T is called the overflow horizon.

Equivalent Formulation

• In the orginal (unscaled) $M_t/M/1$ model;

$$\ell_n = \mathbb{P}\left(X(nT) \ge n\overline{y} \,|\, X(0) = n\overline{x}\right)$$

- Scaling is the usual technique for analysis;
- And for showing figures;

Some Numbers

$$\lambda = 1, A = 0.5, \tau = 1, \mu = 1.5, \bar{x} = 0.1, \bar{y} = 2.0, T = 3.0;$$

n	$\ell_n pprox$
20	1.9e-08
40	1.8e-15
60	2.3e-22
80	3.1e-29
100	4.6e-36

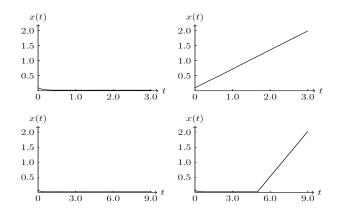
Exponential decay;

Reference Model: M/M/1

- Extensively studied;
- Same problem: $\mathbb{P}(X^{(n)}(T) \ge \overline{y} | X^{(n)}(0) = \overline{x});$
- Large deviations and most likely paths e.g. in classic work of Shwartz & Weiss 95;
- Idea is to adapt for $M_t/M/1$;

Most Likely Paths in M/M/1

- Limiting process $x(t) = \lim_{n \to \infty} X^{(n)}(t)$
- Plot of most likely path [left] and plot of optimal path to overflow at time T [right];
- Top: T = 3; Bottom T = 9;

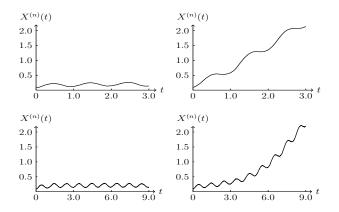


What about $M_t/M/1$?

- First, we use simulation do find empirically the typical paths to overflow;
- Then, we conjecture the optimal paths;
- And give a sketch of proof;
- Next, we apply importance sampling that follows these optimal path to overflow as its average (most likely) path;

Typical Paths in $M_t/M/1$ *by Experiment*

- Experiment: simulate $M_t/M/1$ queue and plot an average path and plot a typical path to overflow at time T; n = 10;
- Top: T = 3 small overflow horizon; Bottom T = 9 large overflow horizon;



Conjecture

Now let $n \to \infty$.

Conjecture

(i). The most likely path satisfies

$$x(t) = \left(\bar{x} + (\lambda - \mu)t + \frac{A}{2\pi/\tau} \left(1 - \cos(2\pi t/\tau)\right)\right)^+, \quad t \ge 0.$$

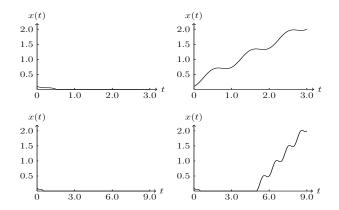
(ii). For small overflow horizon T, the optimal path to overflow satisfies

$$x(t) = \overline{x} + \frac{\overline{y} - \overline{x}}{T}t + \frac{Ae^{\theta}}{2\pi/\tau} \left(1 - \cos(2\pi t/\tau)\right), \quad 0 \le t \le T$$

(*iii*). For large overflow horizon *T*, the optimal path to overflow is concatenation of paths of type (i) and type (ii).

The Plots

- Plot of most likely path and plot of optimal path to overflow at time T;
- Top: T = 3; Bottom T = 9;



Sketch of Proof

Most likely path.

- Let $A_n(t)$ = number of arrivals in [0, t]; $D_n(t)$ = number of departures;
- $A_n(t)$ is Poisson with mean $\int_0^t n\alpha(s) ds$;
- ► $A_n(t)$ can be considered to be a sum of *n* IID Poison RV's each with mean $\int_0^t \alpha(s) ds$;
- Applying SLLN we get

$$\lim_{n \to \infty} \frac{A_n(t)}{n} = \int_0^t \alpha(s) \, ds; \quad \lim_{n \to \infty} \frac{D_n(t)}{nt} = \mu \quad (\mathbb{P} \text{ a.s.})$$

▶ Thus, the scaled queueing processes satisfy for large *n*

$$X^{(n)}(t) \approx \left(\overline{x} + \frac{1}{n} \left(A_n(t) - D_n(t)\right)\right)^+ \approx \left(\overline{x} + \int_0^t \alpha(s) \, ds - \mu \, t\right)^+$$
$$= \left(\overline{x} + (\lambda - \mu) \, t + \frac{A}{2\pi/\tau} \left(1 - \cos(2\pi t/\tau)\right)\right)^+, \quad t \ge 0.$$

Sketch of Proof (cont'd)

Optimal path to overflow at small overflow horizon;

- The heuristic is that the optimal path to overflow equals the most likely path under a change of measure (COM);
- The COM is the same as for the M/M/1: arrival and service rates

$$\alpha^*(t) = \alpha(t)e^{\theta}; \quad \mu^* = \mu e^{-\theta},$$

• With e^{θ} equals as in M/M/1 where it is known that

$$e^{\theta} = \frac{\overline{y} - \overline{x} + \sqrt{(\overline{y} - \overline{x})^2 + 4\lambda\mu T^2}}{2\lambda T}$$

Reason as previous slide that under the COM

$$\lim_{n \to \infty} \frac{A_n(t)}{n} = \int_0^t \alpha^*(s) \, ds$$
$$= e^{\theta} \left(\lambda t + \frac{A}{2\pi/\tau} \left(1 - \cos(2\pi t/\tau) \right) \right) \quad (\mathbb{P}^* \text{ a.s.}),$$

Sketch of Proof (cont'd)

Calculus:

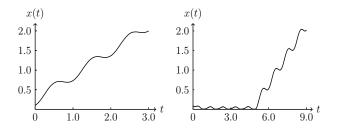
$$\lambda e^{\theta} - \mu e^{-\theta} = \frac{\overline{y} - \overline{x}}{T}.$$

► Thus for large *n* we get

$$\begin{aligned} X^{(n)}(t) &\approx \bar{x} + \frac{1}{n} \big(A_n(t) - D_n(t) \big) \\ &= \bar{x} + \lambda e^{\theta} t + \frac{A}{2\pi/\tau} \big(1 - \cos(2\pi t/\tau) \big) e^{\theta} - \mu e^{-\theta} t \\ &\approx \bar{x} + \frac{\bar{y} - \bar{x}}{T} t + \frac{A e^{\theta}}{2\pi/\tau} \big(1 - \cos(2\pi t/\tau) \big), \quad 0 \le t \le T \end{aligned}$$

Importance Sampling

- Based on the COM of the previous slide for small overflow horizon;
- Large overflow horizon: regular simulation until a time τ (same as in the M/M/1 queue); COM on [τ, T];
- Plot the average paths under this COM for n = 100;



Importance Sampling Estimator

• The (single-run) IS estimator of ℓ_n is

$$L_n = W(\mathbf{X}^{(n)}) \mathbb{1}\{X^{(n)}(T) \ge \overline{y}\},\$$

- Where $\mathbf{X}^{(n)}$ is the path on [0, T] simulated under COM;
- ► And where W(X⁽ⁿ⁾) is the associated likelihood ratio;
- The final IS estimator is based om M repetitions:

$$\widehat{\ell}_n = \frac{1}{M} \sum_{k=1}^M L_n^{(k)}.$$

Performance of IS Estimator

Demand that estimator is accurate

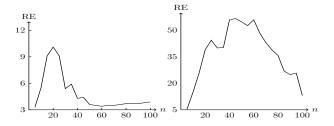
$$\mathbb{P}(|\widehat{\ell}_n - \ell_n| < 0.1\ell_n) > 0.95.$$

- Determine the required sample size M for this;
- From Chebyshevs inequality: $M = O(RE^2[L_n]);$
- Where relative error $\operatorname{RE}[L_n] = \sqrt{\operatorname{Var}[L_n]}/\ell_n$.
- Strong efficiency when relative error is bounded;
- Weak efficient when relative error is subexponential (e.g. polynomial);
- ▶ NB: regular Monte Carlo has exponential relative error.

Numerical Results

- Experiment: n = 5, 10, ..., 100;
- T = 3: sample size M = 20000; T = 9: sample size M = 100000;
- Repeated 100 times;
- Plot of the average estimated single-run relative errors $\widehat{RE}[L_n]$;

• Left
$$T = 3$$
; right $T = 9$;



Conclusion and Outlook

- $M_t/M/1$: simple queue with time-dependent arrival rate;
- ▶ Rare event analysis and large deviations rely on M/M/1 results and heuristics;
 - Challenge for rigid analysis;
- Importance sampling algorithms show empirically to be efficient;
 - · Large overflow horizons worse than small overflow times;
 - Needs a rigid analysis of efficiency;
- Possible extensions
 - More general models (varying service rates; more servers);
 - Other rare events (maximum in busy cycle);